

Series of devices

iMod + PLC Instructions



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Chapter 1 Introduction

iMod NPE running on the platform has the ability to work as a PLC. To this end, beyond the internal configuration file, use the application ClassicLadder used to convert the ladder language LD to Clanguage.



Chapter 2 Prepare the work environment



to achieve the functionality of the PLC on iModzie need:

- 1. Linux or program for virtual machines, such as <u>Oracle VirtualBox</u> with the image of the <u>Linux</u>'a
- 2. software <u>ClassicLadderDesign</u>
- latest version of iMod ENGIN NPE platform (more on this in the chapter devoted to the preparationapplication) <u>iMod</u>

project files used in this manual are on the server ftp:adres: ftp.a2s.com login: npe_imod@ftp.a2s.pl: password npe_1m0d

Linux on any system (virtual-box + image)

To build an application PLC system is needed to support Linux GTK + desktop environment.

Linux can be run directly from Windows using a virtual machine.

VirtualBox can be downloaded from: https://www.virtualbox.org/

Linux image can be downloaded from: http:// virtualboxes.org / images / ubuntu /

1 Start VirtualBox



second Stsackcloth new virtual machine by clicking the new

third Name the virtual machine, operating system, Linux, and select the appropriate version of the

fourth Assign min. amount of RAM for the virtual machine (256 MB)

5 Select'ExistingHard Drive' and select the image file of Ubuntu

User iMod + PLC

Mark Street		- S	×
Create New Virtual Machine		8 mar	
Virtual Hard Disk			
If you wish you can now add a start-u one from the list or from another locat	p disk to the new machine. ion using the folder icon.	. You can either create a new virtual disk o	or select
If you need a more complex virtual dis once the machine is created.	k setup you can skip this ste	tep and make the changes to the machine	settings
The recommended size of the start-up	disk is 8,00 GB .		
Create new bard disk			
 Use existing hard disk 			
ubuntu-9.04-x86.vdi (Nor	rmalny, 10,00 GB)		• 🗔
		<u>N</u> ext	Cancel

6th After the correct image is loaded, a dialog with the parameters of virtual machines. Right click on the added virtual machine and select the "Start".





Password and login to Linux should be used in place of download. For Ubuntu Linux version 9.04: login:ubuntu: password reverse

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application Ladder Design



For purposes of this instruction was used ClassicLadder program.

Classic Ladder software can be downloaded from:

http://sourceforge.net/projects/classicladder/

or from ftp.a2s.pl

to add new elements in the ladder in the application, run the editor window: *View-> Editor Window -> " Modify*

"inthewindow, *Properties* you can give the address of the variable and possibly other parameters of the function block.



Please note that before writing your project, thewindow, *Editor* exit the edit mode by clicking **OK**.

Configuration

To enter the configuration settings you must go to the PLC \rightarrow Configuration

📝 ubuntu (Uruchomiona) - Oracle VM VirtualBo	x
Maszyna Widok Urządzenia Pomoc	
📫 Applications Places System 🕹 😭 😧	Witte Feb 28 8-03 AM ubuntu M Witte Feb 28 8-03 AM ubuntu M
	Config Config
Period/Sizes/Info Events Config Physical Inputs	Physical Outputs Modbus communication setup Modbus slaves setup
Modbus master Serial port (blank = IP mode)	
Serial baud rate	9600
Serial nbr. data bits	05060768
Serial parity	None ○ Odd ○ Even
Serial nbr. stops bits	● 1 ○ 2
After transmit pause - milliseconds	100
After receive pause - milliseconds	٥
Request Timeout length - milliseconds	3000
Use BTS signal to send	● NO ○ YES
Modbus element offset	○ û ● 1
Debug level	○ QUIET ○ LEVEL 1 ○ LEVEL 2 ⑧ VERBOSE
Read inputs map to	୦% B୦% Q ●% I
Read coils map to	୦% 8 🖲 % ପୁ୦% ।
Write coils map from	୦% B 🖲 % Q ୦% I
🔳 🗉 Spy bools vars 📄 Section Disp	Sections Ma Editor Config

tab *Modbus communication setup* set the communication parameters of the device. At the time of leaving an empty field *Serial Port Modbus*master, the communication will take place through an Ethernet interface.

🗘 Applic	ations Places System	Change system appearance	i 🛒 📢 Tue Feb 28, and behavior, or get help	8:04 AM ubuntu 🕻
Period/Siz	es/Info Events Config Ph	ysical Inputs Physical Outputs	Modbus communication setup	Modbus slaves setu
Slave N°	Slave Address	TCP/UDP mode	Module Informations	
0:	0.0.0.0:502	UDP instead of TCP		
1:		UDP instead of TCP		
2 :		UDP instead of TCP]
3 :		UDP instead of TCP]
4 :		UDP instead of TCP]
5 :		UDP instead of TCP		
6:		UDP instead of TCP		
7:		UDP instead of TCP		

On the Modbus slaves setup enter the IP address and communication port for the corresponding Modbus slave devices. Please note the ID of theslave.

The IP address of 0.0.0.0 means the local host
Wubuntu [Uruchomiona] - Oracle VM VirtualBox Maszyna Widok Urządzenia Pomoc Applications Places System Image: System<

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Config

Solution

Solutio

None V ReadInputs (to %I)

None

None

None

None

None

None

None

None

None

✓ ReadInputs (to %I)

ReadInputs (to %I)

ReadInputs (to %I)

✓ ReadInputs (to %I)

ReadInputs (to %I)

None Readinatis (to %i) 1 1 1 Spy bools vars Section Disp... Sections Ma... Editor

On the Modbus I / O Setup enter all the parameters, together with addresses
modbusowymi and the type of request. Each parameter must be assigned to
appropriate slave device.



To save changes to configuration parameters, simply close the *Config.*The changes are saved automatically.

IMod

Before performing the following steps, make an application using *softmgr* have the latest software.



Free technical support is always applies the latest stable packages. You can update the iMod engine with thecommand:

update softmgr iMod

In order to move the PLC mode, run the project iModzie ClassicLadder compiled application through the cross arm-classicladder available on theserver. <u>ftpA2s.Com</u> (login and password at the beginning of Chapter 2)



1.Copy files in binary *arm-classicladder* mode,and *projekt.clprj* (project previously created application, PLC) to the directory: / mnt / nand-user /

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2. Assign the appropriate permissions for the file arm-classicladder by the command

chmod 754 / mnt / nand-user / arm-classicladder

- 3. Run the application *arm-classicladder*
 - / mnt / nand-user / arm-classicladder
- 4. Run the project through the application *arm-classicladder*
 - / mnt / nand-user / arm-classicladder project.clprj

PLC application termination is done by breaking the program, the key combination Ctrl + C, or when you restart iMod.



Pagency application restart iMod PLC is interrupted, so it is advisable to add a startup script to the / mnt / mtd / rcs which will auto-start script after reboot the machine.



To run the application locally, go to the menu *PLC* -> *RUN*. With thewindow *var bools Spy* (View -> *var Bools*window)and thewindow *free vars Spy* (View -> *Free var*window),you can control the states and the parameter values3.

Chapter Sample configuration

The sample configuration iMod telemetry module in operation as the PLC will be presented two examples:

- 1. the count changes in the status LEDs on the state USER_LED high
- 2. for the number 10 diosy USER_LED status changes will be sent an e-mail.

First modification of the status LEDs counting USER_LED



In this example, , the application will calculate the amount of state changes and save the diode USER_LED this number to register iModzie.

wbuntu [Uruchomiona] - Oracle VM VirtualBox	
Maszyna Widok Urządzenia Pomoc	
🛛 🏹 Applications Places System 🥹 🎅 🕢 🛛 🗉 🍺 🛒 Wed Feb 2	9, 3:58 AM 🛛 ubuntu 🕑
Section Display (imodplc.clprj)	_ • ×
File Search View PLC Help	
	Display symbols
	V1:=%QW1+1
	(s)
COMPARE	%B0
%IW1>0	(R)
	Ξ.
	~
Section Section Editor	Spy free
	Right Control

used in this application are two main variables:

- IW1 LED read-out of USER_LED
- QW1 save the changesnumber of

and aauxiliary variables:

• B0

are used the function blocks:

- Comparison Variable
- Variable Assignment
- Set Output
- ResetOutput
- InputNC

iMod defaults to storing state I / O because the application was set to count changes in USER_LED diode when the diode is taken at 0 (LED off).



 In the time evolution of LEDs USER_LED to 0, the signal will be released with the help of the function block COMPARE% IW1 = 0 through the normally closed contact with the additional variable B0 and reach first the function OPERATE% QW1: =% QW1 1 and immediately afterwards to the coil SET variableB0.



 With OPERATE function key block, variable QW1 will increase by one. SET coil results in a change of variable B0, which will disconnect the coil normally closed to the variable, so that the signal will not reach to the function block OPERATE. This is a security that QW1 parameter was increased by only onepoint.



 If you change the LED status USER_LED to 1, the variable B0 is reset by means of a function block% IW1> 0, so that the normally closed solenoid is closed again and the next amendment to the state of LEDs USER_LED to 0 will pass the signal.

Configuration

Configuration modbusowej communication (PLC→ *Configuration* → *Modbus communication*setup):

For this example we will connect with the device through the Ethernet port, so Modbus Master Serial Port leave blank, the rest is left to the default settings.

modbusowej addressing configuration

(→ PLC Configuration → Modbus slavessetup):

	Config						
Period/Siz	es/Info Events Config	Physical Inputs	Physical Outputs	Modbus communication setup	Modbus slaves setup	Modbus I/O setup	
Slave N°	Slave Address	TCP/U	DP mode	Module Informations			
0 :	0.0.0.502	UDP ins	stead of TCP iMc	od9300			

Configuration parameters modbusowych

(\rightarrow Configuration \rightarrow PLC Modbus I / O setup):

Ĺ							Conf	ig						_ — X
	Period/Sizes/Info	Ever	nts Config	Physical Inpu	ts Physic	cal	Outputs	Modbus	communica	itio	n setup	Modbus slaves se	etup Moo	lbus I/O setup
	Slave N°			Request Type	5		1st Mod	dbus Ele.	Nbr of Ele		Logic	1st I/Q/IW/QW	mapped	
	0: 0.0.0.0:502	\sim	ReadInp	uts (to %I)		~	101		1		Inverted	1		
	0: 0.0.0.0:502	~	ReadInp	uts (to %I)		~	102		1		Inverted	1]



Pay attention to addressing modbusową. It often happens that the address is shifted by 1 up or down. In this case, addressing ClassicLadder parameters should be postponed for one up off the iMod.

Construction and ConfigurationiMod

ConfigurationiMode exclusively through MainConfig.xml file. First you have to configure the access channels and addressing parameters.

Definition channels

of communication as configured in the program modbusowej ClassicLadder, access channel must be created at modbusowym device 0,via the Ethernet port on the 502nd The source parameters of this device iMod.

```
<? Xml version = "1.0" encoding = "UTF-8"?>
<imod Version="1.1.0">
<group name="Definicje kanalow">
<access-channel name="Modbus_S1">
<protocol name="MODBUS" />
<prot> "ET-502-TCP" </ port>
<property name="device-id" value="0"/>
</ Access-channel>
<source-channel name="NPE_io">
<protocol name="HARDWARE"/>
<gap> 0 </ gap>
<cycle> 2 </ cycle>
</ Source-channel>
```

</ iMod>

Definition of parameters

create two parameters, one responsible for the status LED read-out values USER_LED (parameter d 100), one in which you saved the amount of change of states (the id parameter 101).

```
<IMod version = "1.1.0">
<group name="Definicje kanalow">
      <parameter>
             <id> "100" </ id>
             <description> "USER_LED" </ description>
             <source-channel channel-name="NPE_io" parameter-id="USER_LED"/>
             <access-channel channel-name="Modbus_S1" parameter-id="100">
                    <property name="varspace" value="DISCRETE"/>
             </ Access-channel>
      </ Parameter>
      <parameter>
             <id> "counter" </ id>
             <access-channel channel-name="Modbus_S1" parameter-id="101"/>
      </ Parameter>
</ group>
</ iMod>
```

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Verification example, in

Forverifying the correct application example will use a master Modbus - Modbus Poll

Modbus Poll application is available online at: http://www.modbustools.com/modbus_poll.asp

In addition, upload the configuration file discussed earlier, and run the application *arm-classicladder* together with the draft generated by ClassicLadder.

Establishing a connection

Poll Definiti	on	×
Slave ID:	1	ОК
Function:	03 Read Holding Registers 🔹	Cancel
Address:	101	
Length:	2	
Scan Rate:	1000 ms	
🔽 Auto Rea	ad <u>E</u> nable	<u>R</u> ead Once

must first be set parameters which will be by application Modbus Poll. To do this, go to the Poll Window Definition(*Setup-> Poll*Definition).

In this example, read the slave device that is iMod. His address modbusowy is 1, we use function code modbusowej 03, reads the address registers 100, 101 and 102 because we start scanning for 101 and three addresses (modbusowe shift occurs here.)

Connection		×
		ОК
9600 Baud 💌	Response Timeout	Cancel
8 Data bits 📃 💌	1000 [ms]	
Even Parity 💌	Delay Between Polls	
1 Stop Bit 💌	10 [ms]	<u>A</u> dvanced
Remote Server —		
IP Address	Port	_
192.168.0.131	502	

The next step is to connect to iMod'em (Connection -> Connect .)

According to the configuration file, we connect via TCP / IP andport 502nd

IP defaultiMod telemetry module are: 192.168.0.101

Modbus Poll - [Mbpoll1]	
Eile Connection Setup Functions Display View Window He	alp _ a x
🗋 🗅 🖆 🖼 🎒 🗙 🛅 🖳 🏥 🕮 05 06 15 16 22 23 101 🌹 餐	
Tx = 037: Err = 21: ID = 1: F = 03: SR = 1000ms	
40101 = 1	
40102 = 1	
For Help, press F1. For Edit, double click on a value.	192.168.0.131: 502 🥢

After successfulcombination should display a window like this (depending on the version of Modbus Polla window may vary) .

description of the parameters in the Modbus Poll:

Address	Description
101	LED USER_LED
102	Counter - indicates the number of changes the status LEDs

Write Single Register				
Slave ID:	1	<u>S</u> end		
Address:	101	Cancel		
Value:	1			
Use Function © 06: Write single register © 16: Write multiple registers				

to change the selected parameter, double-click on the address or the displayed value.



To change a parameter value, enter it in the Value window send to device using the Send button. Status LEDs on the device USER_LED should change, and the parameter value 102 should increase by one point.

Second e-mail notification at 10 times the change of status LEDs USER_LED



application will send an e-mail to the address indicated in the configuration file at a time when the value changes LED status exceeds the 10th USER_LED When sending e-mail, the number of changes in diode is reset and the counting is done from the beginning.

🔗 ubuntu [Uruchomiona] - Oracle VM VirtualBox	
Maszyna Widok Urządzenia Pomoc	
🛟 Applications Places System 🥹 🎅 👔 💿 💿 💿 🖓 👘 🖗 Wed Feb 29,	3:59 AM ubuntu 🕗
Section Display (imodplc.clprj)	tch users or shut down
File Search View PLC Help	
	Display symbols
COMPARE %B0 OPERATE %W1=0 %QW1:	=%QW1+1
COMPARE %iW1>0	%B0
%Q0 %TM0 Q R %C1 E 15 P D	°́́́́
	~
Variable: %B0 (%B0)	
Classicla Spy bool Section Sections Editor Spy Spy Spy Section Sections Editor Spy	y free 🔲 🔂 🤕

This application is an enhanced version of the application from the previous example, because all parameters are the same. In addition to the variables which are presented in the previous example, there is an additional variable:

• Q0 - the variable is responsible for sending an email

Program Description

This program counts the number of status changes USER_LED diode, which diode 10 changes state to state, followed by e-mail notification of predefined recipients .



It is used here for the function block counter (Counter Block) and timer (Timer Block IEC). The block counter is set to run after and send a signal to the coil% Q0 when the number of counts is greater than



- 1. 10when USER_LED status is zero, the signal comes to the counter to Ujoints, raising the number 1 (to be paid note that this is a one-time change and security need not be applied as before).
- 2. At the time when the number of changes will be 10, the output signal D will be announced at launch coil% Q0. The parameter Q0 is responsible for sending mail.
- 3. Commissioning of high resets the counter to be able to start counting from the beginning. However, before the counter is reset, the state of the high passes to the timer, which is set to one second.
- 4. Only after one second timer is reset. Please use it too fast because the counter reset, it may not have time to read iMod parameter Q0 and thus send a message.

Configuration

and communication configuration modbusowej modbusowej addressing configuration remains unchanged.

For modbusowych parameter configuration, add a new variable

(PLC → Configuration → Modbus I / Osetup)

						Con	fig					_ - ×
Period/Sizes/Info	Ever	nts Config	Physical	Inputs	Physica	l Outputs	Modbus	communica	ation setup	Modbus slaves se	etup Mod	bus I/O setup
Slave N°			Request	Туре		1st Mo	dbus Ele.	Nbr of Ele	Logic	1st I/Q/IW/QW	mapped	
0: 0.0.0.0:502	~	ReadInp	utRegs (to) %IW)	\sim	101		1	🗆 Inverte	d 1]
0: 0.0.0.0:502	\sim	WriteHo	dRegs (fro	om %Q	N) \~	102		1	🗆 Inverte	d 1]
0: 0.0.0.0:502	~	WriteCoi	ls (from %	6Q)	\sim	103		1	🗆 Inverte	d 0]



Pay attention to the 1st column mapped - in this case is set to zero so that the variable Q0 begins with the number 0 and not as before, the variables start from 1

Building configurationiMod

iModconfiguration file is a file extension the previous example. Channels and parameters, add the appropriate lines of code.

Definition

Channeldefinition channels to add a notification channel, which will be in the configuration of mail and email message content channel.

User iMod + PLC

The definition of parameters

to get the functionality to send e-mail after 10 times you send an e-mail, add the parameter responsible for sending e-mail after the change of state.

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Verification example, in

Forverifying the correct application example will use a master Modbus - Modbus Poll

Modbus Poll application is available online at: http://www.modbustools.com/modbus_poll.asp

Additionally, you should upload the configuration file discussed earlier and run the application arm-classicladder together with the draft generated by ClassicLadder.

Establishing a connection

Poll Definition	on	×
Slave ID:	1	ОК
Function:	03 Read Holding Registers 🔹	Cancel
Address:	101	
Length:	3	Apply
Scan Rate:	1000 ms	
🔽 Auto Rea	ad <u>E</u> nable	<u>R</u> ead Once

must first be set parameters which will be by application Modbus Poll. To do this, go to the Poll Window Definition(*Setup-> Poll*Definition).

In this example, read the slave device that is iMod. His address is 0 modbusowy We use function code 03 modbusowej Addresses for the reading to the address registers 100, 101 and 102 because zaczynij scanning for 101 and three addresses (modbusowe shift occurs here.)

TCP/IP	Mode @ RTU (ASCI	ОК
3600 Baud	- Response Time	anut	Cancel
Data bits	1000 (n	ns]	
Even Parity	Delay Between	Polls	-
Stop Bit _	- 10 (n	ns]	Advanced
Remote Server-		land	
Address	P	-on	

The next step is to connect to iMod'em (Connection -> Connect).

According to the configuration file, connect to TCP / IP andport 502nd



IP defaultiMod telemetry module are: **192.168.0.101**

verification of the example

Modbus Poll - [Mbpoll1]	×
Eile Connection Setup Functions Display View Window Help	Б×
🗌 🗅 🖆 🖬 🎒 🗙 🛅 🗒 🚊 🕮 05 06 15 16 22 23 101 💡 隆	
Tx = 857: Err = 22: ID = 1: F = 03: SR = 1000ms	
40101 = 1	
40102 = 1	
40103 = 0	
For Help, press F1. For Edit, double click on a value. 192.168.0.131:	502 //.

After successful combination should display a window like this (depending on the version of Modbus Polla window may be different).

description of the parameters in the Modbus Poll:

Address	Description
101	LED USER_LED
102	Counter - indicates the number of changes the status LED
103	Counter - when this parameter reaches a value of 10 will send a notification email and the value is reset

Write Single Re	×			
Slave ID:	1	<u>S</u> end		
Address:	101	Cancel		
Value:	1			
Use Function © 06: Write single register © 16: Write multiple registers				

to change the selected parameter, double-click on the address or the displayed value.



To change a parameter value , enter it in the Value box then send to the device through the Send button. Status LEDs on the device USER_LED should change, and the value of the parameters 102 and 103 should increase by one point.

At 10 times the change of status LEDs USER_LED iMod application sends an e-mail to the addressdefined.

User iMod + PLC

Email_sender:101

Od: testnpe@o2.pl (więcej) dnia: 13 marca 2012 13:36

USER_LED change state 10 times

Appendix A: Description of the function blocks the Classic Ladder

Symbol	Description	Function
$\dashv \vdash$	Pinnormally open	signal leads the(closes contacts), the value of the variable is assigned a logical "1"
-1/	Normally closed	Normally closed. Leads the signal (contact closes) when the value of the variable is assigned a logical "0"
-1/1-	contact with the rising edge of	this contact sends a pulse when the status changes from open to close
-M-	contact with the falling edge of	this contact sends a pulse when the state changes from a closed to an open
	line connectinghorizont al	The horizontal line connecting theelements of the
	line connecting the vertical	vertical line connecting the elements of
\rightarrow	a horizontal line connecting the end	creates a horizontal line to the end of
ΤM	the timer function block	Timer, selectable timer name, value, fixed, and mode: • ON • OFF
C	function block	Counter R-counterreset counter P-sets to the reference value to output was 1 U-counting up the D on the left - counting down the D on the right - the output when the counted value is equal to or greater than the set point is the state of a
>	comparison function block	using the block You can use the mathematical comparison of

User iMod + PLC

Т	the timer function block	Timer counts down the time specified.
М	monostable block	This block sets the output to "1" for a certain time and then obtains the output state "0"
-0-	normally opencoil	relaysets the value assigned to the variable to "1", when you are given a signal. This is a relay with the contacts open.
-Ø-	Normally closedcoil	relaysets the value assigned to the variable to "0" when you are given a signal. It is a compact relay with contacts.
-\$)-	coilsetting	Adjustablerelay"SET". The relay is set to "1" variable.
-®-	Resetcoil	relayadjustable "RESET" designed work towith the relay, "SET". When the relay is given the signal value of the variable assigned to it will be set to "0".
-©-	Coil jump	Jump to the selected line
-©-	coil call	call the selected line
=	operation	The ability to perform mathematical operations
R	Gross	Net